Organizational Principles for Embryological and Neurophysiological Processes 1

Michael A. Arbib
Department of Computer and Information Science
Technical Report 70C-2
University of Massachusetts
Amherst, Mass. 01002

ABSTRACT

The author argues for the development of organizational principles for multicellular assemblies to complement the approach of molecular biologists to cellular mechanisms, and notes that such development requires an inductive phase before detailed deductions can be useful. lle notes the challenge posed by neural specificity to theorists of embryological development, and suggests "layered somatotopy" as a useful organizing principle for brain theory.

To be published in the proceedings of a conference on Physical Principles of Neural and Organismic Behaviour [held 16-18 December 1970 at the Center for Theoretical Studies, University of Miami, Coral Gables, Florida.] Preparation of this paper was supported in part by the Public Health Service under Grant No. 1-RO1 NS 01092-01 COM from the National Institute of Neurological Diseases and Stroke.

Organizational Principles for Embryological and Neurophysiological Processes 1

Michael A. Arbib
Department of Computer and Information Science
Technical Report 70C-2
University of Massachusetts
Amherst, Mass. 01002

ABSTRACT

The author argues for the development of organizational principles for multicellular assemblies to complement the approach of molecular biologists to cellular mechanisms, and notes that such development requires an inductive phase before detailed deductions can be useful. He notes the challenge posed by neural specificity to theorists of embryological development, and suggests "layered somatotopy" as a useful organizing principle for brain theory.

Reprinted with permission of Gordon & Breach Science Publishers, Inc.

To be published in the proceedings of a conference on Physical Principles of Neural and Organismic Behaviour [held 16-18 December 1970 at the Center for Theoretical Studies, University of Miami, Coral Gables, Florida.] Preparation of this paper was supported in part by the Public Health Service under Grant No. 1-R01 NS 01092-01 COM from the National Institute of Neurological Diseases and Stroke.

This paper is dedicated to the memory of Donald M. Wilson whose research on insect flight and locomotion combined incisive experiment with theoretical insight. His untimely death in a "rough river" boating expedition has saddened all of us who valued his friendship and had looked forward to enjoying his company and sharing his insights many times in the years ahead.

1. Approaches to Theoretical Biology. 2

There seem to be two main directions whereby the physicist can approach biology. In one, he tries to do conventional physics as long as he can, and gets into the biophysics of DNA, say, whence he finds himself slowly growing into molecular biology, and, hopefully, thence into the principles which govern the interactions of cells and the growth of those interactions. A second, more romantic, approach is to start from questions about overall function of body and mind, and try to find mechanisms in terms of which one could answer them, and so go down, for example, to explore what sort of brain functions we would need for intelligent behavior, and thence to the neural structures that could subserve those functions.

To point up this distinction between going "up" from the basic biochemistry and physics and going "down" from overall functional questions, we might well look at Computer and Information Science, where we see a very marked division of labour. On the one hand, we have the electrical engineer using solid-state physics in trying to push to the ultimate reduction of size, increase in speed of operation and flexibility of function for devices which are then to be built into

In this section I indulge in a long-winded discussion of some problems in the philosophy of science raised by the interactions between experimentalists and theoreticians at the conference. Some readers may wish to turn directly to Section 2.

computers. However, the computer scientist, having got those components, is not at all concerned with the actual physics involved. He wants to be guaranteed that the components have certain functions, but then his concern is to figure out how to put together large scale organizations in terms of those component functions to get some overall sophisticated function. Thus, the component level - or the cellular level, to be more biological about it - is the meeting ground for two quite different approaches. To explain how cells "work", and their capacities for interaction, is the task of the biophysicist and biochemist. On the other hand, understanding how to organize large collections of such components seems to require such approaches of Computer and Information Science as automata theory and computer simulation.

To make this distinction another way, we may recall those happy days a few years ago when having "cracked the genetic code" many people talked (at least to the popular press!) as if all biological mysteries were solved, at least in essence, and some people were not joking when they talked of "cracking the brain code". Now that we have had some years to reflect upon the "cracking" of the genetic code, we well realise that the transduction from DNA via RNA to amino acids does not explain all the wonders of cellular behaviour, let alone the complex dynamics of embryology. No more will finding out in great detail the functional characteristics of neurons solve all the problems of neural organization.

By now, many hitherto mysterious properties of cells - the basic "components" of all organisms - have been explained in terms of biochemistry and molecular biology, and many papers in these <u>Proceedings</u> document the power of such explanations. It would be foolish to try

to belittle such achievements, and I do not wish to do so - but I do wish to caution the reader against the all too common mistake of being so dazzled by their success as to believe that biochemistry alone can unravel all the knotty problems of biology, and that the development of new theoretical approaches is unnecessary. I believe that some of the less subtle research on the chemistry of memory amply testifies to the dangers of such a view. We all agree that cells are living systems and that learning involves changes in the brain, and thus,in some sense - learning is a growth phenomenon. Thus it is hardly surprising that substances which block RNA synthesis - and thus cell growth - interfere with an animal's learning. But to go from this to making statements like "Therefore, RNA is the memory molecule" is as useful as noting that cutting off the electricity supply disrupts the storage of information in a computer and deducing that "Therefore, electrons are the building blocks of memory". We have a theory of complex computer memory structures based on the properties of the switching and storage elements. It is irrelevant to this theory whether component properties are mediated by electrical, magnetic, hydraulic or chemical mechanisms. Similarly a theory of the brain will not be so much in terms of biochemistry as in terms of organizational principles for neurons. Biochemistry is irrelevant to such a theory of organization per se - but is vitally important in helping us understand the detailed properties of these components. In studying human perception, biochemistry may be of little relevance, while organizational principles predominate. In studying drug therapy, precisely the opposite balance may hold.

In the rest of this paper, I shall stress the search for organizational principles, but do not try to argue the superiority of

this approach to that of the molecular biologist, but rather argue the complementarity of the two approaches. In fact, even in the sketchy presentation that so short a paper as this decrees, we shall often see the organizational approach - "If cells can do such-and-such then an array of them with certain properties will develop or process information in a way which is thus explained" - immediately raising complementary questions - "Is it physically possible for a cell to do such-and-such, and if so what biochemical mechanisms are involved?"

The failure to note this complementarity and instead argue for the superiority of one's own approach led to certain tensions at the conference itself³, perhaps expressed most noticeably in the desire of a few experimentalists to discredit all theoretical efforts which were not slavishly tied to experiment - forgetting that new concepts and paradigms are often required before experiments can be designed which extract really meaningful data. [Incidentally, there is a certain delicious irony in the chiding of some biologists against over-involvement in theory, for at other conferences, some mathematicians complain that over-involvement with physical intuition distracts from the cool algebraic beauty of purely formal deductions within an axiomatic system. However, one may suggest - somewhat presumptiously, perhaps - that it may be possible to converge eventually upon some judicious balance of intuition and theory which will yield enough understanding to compensate for such chiding!]

Here, and elsewhere in this Section, I am building a "straw-man" whose demolition will bolster my arguments. I hope that no conferee, noting a straw or two of his own, will make the hurtful mistake of believing that the whole assemblage is intended as an unkind reconstruction of his overall viewpoint.

The real cleavage which emerged at the conference was not, perhaps, that between experiment and theory, but rather that between science and technique. The scientist seeks for understanding and will use whatever blend of theory and experiment seems best to match his intellect to the task at hand, while the technician seeks to apply a technique he has mastered. Sometimes the technique is appropriate to the task, and the lucky technician may bask in the glow of scientific achievement. But all too often the technique is good for nothing but producing irrelevant papers - be they by the experimenter-technician pumping drugs to be assayed in cat after dying cat, or the theorist-technician using the mathematics of physics to churn out equation after tedious equation assessing the progress of a Hamiltonian which has little relevance to the organism it is posited to represent.

Perhaps with this distinction in mind, we can see one of the greatest pitfalls facing the physicist turning theoretical biologist.

Too much of his education has involved his mastering long-polished mathematical techniques, and finding that wide classes of problems can be solved simply by "plugging-in" these techniques. With this as background, it is all too easy to believe that he can solve the biologist's problems by the technician's approach (though he will think it is scientific) of "plugging-in" these techniques to biological situations, little realizing that a great period of induction and experimentation (yes, even theorists must experiment - even if only with symbolic constructs) was required to match technique to problem. But theory is required in biology - as in any science where constructs become subtle enough to escape the domain of the immediately observable and where the depth of argument comes to exceed the usual grasp of common sense - and

what remains to be determined is not whether there shall be theoretical biology, but rather what forms theoretical biology shall take. The theorist who can make a substantial contribution will probably be one who combines an intimate knowledge of the experimental data of some restricted problem in biology with a broad command of theoretical techniques, and uses the interaction between his reformulation and reconceptualization of the data and his reworking of the techniques to evolve genuinely new insights into that particular biological problem only to find that those insights are valid elsewhere. There is no recipe for this.

2. Neural Specificity and Theoretical Embryology

We cannot understand the central nervous system unless we understand to what extent we are dealing with a genetically determined structure and to what extent we are dealing with a loosely specified structure which is to be shaped by adaptation. In fact, we now know that there is a great deal of specificity in the organism and in particular in the nervous system, and the papers of Ede, Schroeder and Laing (this volume) give some rather detailed ideas about the experimental and theoretical tools with which we can determine the mechanisms which give rise to that specificity.

Until perhaps 1940, a popular view of the nervous system was as an essentially random network. The idea was that if a creature, with adequate receptors and effectors, were put in some complicated environment and "punished" when it did something "wrong" and "rewarded" when it did something "right", then eventually the correct connections would be made to enable the organism to function effectively in its environment. Such a belief was based on rather gross observations upon humans with polio who had a flexor muscle, say, wither away and had had the remaining healthy extensor muscle cut in two and so sutured that half the muscle kept its old function of extension while the other half now had the opposite function of flexion. After extensive therapy, patients were able to adapt the muscle to its new use, so long as they were carrying out careful voluntary movements. By extension from these results, many people thought the nervous system was completely "plastic" - i.e. that all connections could be - and in fact were - moulded by experience. We owe to Paul Weiss and Sperry

and other workers the knowledge that plasticity is <u>not</u> unlimited, and that in fact there is a great deal of neuronal specificity - ie.

genetics constrains many details of neuronal connections which cannot be changed by experience unless there exist specific brain structures to exploit that experience.

On the other hand, a newborn baby has to be able to suck, to breathe, to excrete and so on. It cannot do many other things at birth, but has to be able to learn how to do them, and this cannot happen unless it has appropriate structures to implement learning. This point may seem obvious, but is so often lost sight of that it may pay to belabour it with an obvious example. Think of tossing a coin repeatedly. Every time it comes up heads, spray it with Chanel No. 5, and every time it comes up tails spray it with stale cabbage juice. It hardly seems profound to doubt that the coin will eventually tend to come up heads rather than tails, but it may be helpful to explicate the grounds for our doubt.

Firstly, the coin does not have receptors which allow it to distinguish Chanel No. 5 from cabbage juice. Secondly, even if it could distinguish them, it has no inbuilt criteria to determine which is preferable. Thirdly, even if it could tell which was preferable it has no mechanism whereby it could make use of that knowledge to change its behaviour. Thus, in looking at the embryology of the nervous system we have to look for specificity, whether in the direct sense of determining networks which will mediate innate behaviour patterns, or to provide the adaptational substrate to enable the organism to adapt its evolutionary heritage to the

exigencies of its own environment. We have to understand how appropriate receptor and effector arrays can be structured, how basic drive mehcanisms can be "built into" the organism so that it can shape its behaviour on the basis of some evolutionarily determined criteria of biological usefulness or destructiveness, and we must understand - at least in mammals - the determination of a sufficiently rich cortical structure to allow sophisticated learning. To enhance the latter point by a striking contrast, we may recall Paul Weiss' [1941, for an overview] intriguing experiments in which the forelimbs were reversed in the larval stage. When the salamander grew to salamanderhood then, whenever it would see some food in front of it, the brain would send the appropriate command of "advance", but unfortunately the neural circuitry in the brainstem which interpreted the command did not "know" that the forelegs were back-to-front and so would send the sequence of muscular activation which would cause the forelimbs to try and make the animal scurry away from its food. No matter how long the animal was exposed to this unfortunate situation it could never learn what was wrong - or, at least, if it learned what was wrong, it could not do anything about it. Thus we see the necessity for adequate structure if learning is to ensue.

Notice that what we are talking about in the nervous system is not the development of individual organs per se, but rather the development of functional systems which involve the whole organism. The animal at birth has to be able to take tactile stimuli on the lips and go through the "computation" required to convert this into a sucking reflex. If we look at animals such as the guinea pig in which the hindlimbs are more important than the forelimbs at birth

we will find the uneven development of the spinal cord which insures that the hindlimbs are ready to function at birth. This is what the Russian physiologist Anokhin [1964] refers to as systemogenesis we have to think of the nervous system not in terms of anatomically defined lumps of tissue, but rather in terms of an interacting overlapping collection of systems for carrying out biologically important functions. Thus, our task becomes even more complicated when we realize that it is not enough to look at one small part of the body or the nervous system and explain how it grows, but we have to explain the sort of synchrony which allows functioning systems of various kinds to be available at birth and at later stages of maturation. The models of Ede and Schroeder are at the simpler stage of studying morphogenesis of single organs - this seems to be a necessary way-station in the evolution of our models before we can tackle the synchrony problems of systemogenesis. At the moment, we look at one organ in a system and try to explain what sort of cellular interaction can give rise to its shaping. We may hope that, later on, when we understand this, we will have the intellectual apparatus in place to combine together our models of several systems to understand what sort of overall mechanisms allow coordination of their development.

Having established, in Section 1, the cellular level as an appropriate intermediate between the study of macromolecules and organelles by the biophysicist and biochemist, and the study of organismic control by the computer and information scientist and having now seen the interest of understanding embryological processes, let us briefly mention some of the mechanisms at the cellular level

which shape the overall form of the organism, including that of its nervous system. (The reader will find an excellent overview of "the forces that shape the embryo" in Trinkaus [1969].)

One mechanism whereby a tissue may change its form is that of the autonomous change in cell shape. For example it is now well-known that various microstructures may be synthesised within cells during characteristic changes of shape, and that their destruction impairs such changes. Thus cells seem able to elongate themselves by producing microtubules aligned parallel to the axis of elongation. Again, cells seem able to constrict a portion of themselves by producing microfilaments which can then contract to provide the constriction by a sort of "purse-string effect" [Baker and Schroeder, 1967]. Schroeder [1970, 1971] has combined such mechanisms to provide an elegant model of neurulation - the process whereby a plate of cells on the back of the embryo is formed into a trough which then rolls up into a tube running the length of the embryo to then disappear beneath the surface of the back and form the rudiments of the spinal cord and brain. A crude caricature of the mechanism is shown in Figure 1 - the reader will find a more subtle and careful treatment in Schroeder's paper in this volume.

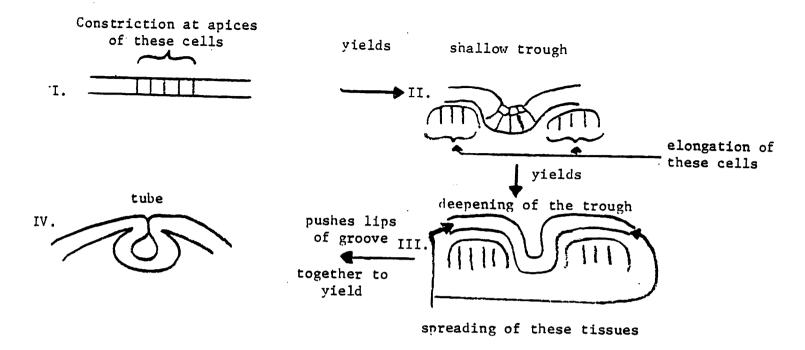


Figure 1

Dangerously oversimplified schematic of neurulation. The 4 stages are not chronological. Rather, each of the 3 transitions schematises a mechanism (there are others) found by Schroeder [1970] to play a role in forming the neural tube. All views are in cross-section.

Another mechanism whereby a tissue may change its form involves the combined effects of cellular adhesiveness and cellular motility. Such a mechanism helps us understand situations in which the attachments of cells change over time, but where there seem to be important specificities in the ensuing pattern of cellular attachments.

Gustafson and Wolpert [1967 - for an exposition see also Wolpert and Gustafson, 1967] have given a masterly analysis of cellular movement and contact in sea urchin morphogenesis. Ede and Agerbak [1968] have been able to correlate changes in adhesiveness of cells (and the consequent change in their motility) in normal and talpid mutant chick embryos with changes in the developing limit pattern in these embryos, while Ede and Law [1969] (see also Ede [1971]) have expressed this correlation in the specific form of a computer simulation of limb development.

While elegantly showing how changes in cell shape, motility or adhesiveness can provide mechanisms for morphogenesis - both in the nervous system and elsewhere - the above schemes do not make explicit how a cell "knows" what contribution it is to make in the overall pattern. It is for this reason that other workers have developed the idea of "positional information". Here, the line of argument runs "If the cell is to change appropriately it must have information about its position within the embryo (and perhaps it will need to consult a clock, too)." An early approach to such positional information was in gradient theory (e.g. Child [1941]) - if a source of some metabolite were located at one end of the axis and a sink at the other, with a uniform gradient in between, then the concentration of metabolite in any cell would signal its position on the axis. Wolpert [1969] has

suggested ways in which such a model needs refinement and elaboration, and Goodwin and Cohen [1969] have instantiated Wolpert's ideas in a model in which position is signalled by the phase differences between families of pulses propagating with different delays from cell to cell. By contrast, automata theorists have shown how cells may be formed into complex arrays without explicit "addressing". Rather, each cell is capable of a finite number of states, and at any time the cell changes state in a way dependent upon its previous state and that of its neighbors. For example, vonkeumann [1966] exhibited a self-reproducing array with tens of thousands of components, but the cells were only capable of 29 states, and so could not "know where they were". Arbib [1967] has attempted to place this approach in a more biological context. The work of Apter [1966] should also be mentioned here. Other authors have compared the change of state rules used by vonNeumann and others to the rewriting rules employed by linguists to "grow" a sentence from its grammatical description, and are now exploring the applicability of formal linguistics to theoretical embryology (Lindenmayer [1968], Laing [1969, 1971]).

In considering the specificity of cellular connections, we must not be misled by estimates that the amount of information in DNA is far less than that contained in the connections of the brain, which some have taken to imply that connections in the brain must be random. To see this, consider the following computer program which comprises four instructions:

- Set n equal to zero.
- 2. Print out n.
- 3. Replace n by n + 1

4. Return to the first instruction.

If you observe a computer executing this program, it will emit a stream of numbers which is endless - at least till you have exhausted the capacity of the computer. Arguments that a comparison of the number of DNA bases with the number of connections in the brain shows that the brain must be a random network is as naive as comparing the four instructions of the above program with the number of positive integers and concluding that the sequence of positive integers is a random sequence! In other words, one of the things we know from our study of programming computers to do clever things, is that our programs have loops within them which are hierarchically structured to provide for a great deal of economy in the way we specify processes. As a biological example of a plausible "use" of such "nested subroutines", we may cite the retina of the frog. The connections between the interneurons of the second layer in the retina and the ganglion cells which send their output down the optic tract to the brain have been schematized by Lettvin and Maturana as falling into two or three segregated layers. A plausible wiring scheme would then prescribe that certain types of axons from the interneurons terminated in one layer and so are highly likely to connect one level of the dendrites of the ganglion cells while other types of axons bearing different transforms of the visual input would terminate in the other layer thus hitting other parts of the ganglion cell dendrites. By this means, one can very simply specify how to get a retina that would function perfectly for the frog trying to snap flies in its world, without having to specify point-by-point interconnections. Hence, a sort of "nested subroutine" approach could probably explain a great deal of the specificity of the nervous system without requiring an immense investment in genetic material. In the next section we shall see - among many other facts - that such economy of genetic prescription augurs well for economy of functional description when we come to describe organizational principles for neurophysiological processes.

3. Implications for Brain Modelling

Having gained some idea of the specificity of structure there is in the nervous system let us see the effect our views of brain structure will have upon our approach to modelling brain function.

In certain invertebrates, we may find that the function of the system we wish to explain is mediated by a rather small neural network and so we might actually hope to track down, by explicitly simulating the behaviour of say 100 or so neurons, all the details of their interaction, and so obtain a plausibly complete explanation of how a locust, say, walks or flies. (See, for example, the beautiful review of 'Insect Walking' by Donald Wilson [1966])

When we turn to vertebrates, this strategy does not work, save in studies of peripheral circuits for muscle control, for there are just too many neurons. There are various strategies to take, depending on our ideas about structure, as to how one might make a model. The physicist has one ready answer for how we might model a system with millions or even billions of neurons. From his study of gases he would suggest statistical mechanics [or - in technical terms -"average the hell out of it".] Unfortunately, such averaging may destroy the very parameters of interest to us if we want to explain linguistic behavior or coordinated motor behavior as in a frog snapping at a fly. On the other hand, if we want to understand how the cooperative behavior of many billions of neurons in the cortex gives rise to evoked potentials or electroencephalograms, then some sort of statistical mechanical approach may well be worth while. However, a straightforward statistical approach to the every large system will not do for more detailed structural questions about complex information processesing

in brains.

In this context, it may be worthwhile to contrast two types of statistical models. Winograd and Cowan [1963] were concerned with the fact that in as large a system as the brain one has both the likelihood of not specifying completely all neural interconnections accurately by genetic parameters and also the likelihood of many "malfunctions" of components during actual information processing by the system. They wished to design networks with enough redundency to insure that the organism would not be too unreliable. Their strategy was to start from a very specific function they wanted a hypothetical "nervous system" to undertake, and then provide ways in which they could transform this "nervous system" into a new form which was sufficiently redundant that quite a lot of sloppiness in the "wiring" and in the behaviour of the "neurons" would still give correct overall function. This strategy of starting from a specific structure for computing some function and finding ways of introducing redundancy to make it resistant to certain types of damage both in growth and function is radically different from the strategy Cowan [1969] took in his later work, in which he looked at interactions between thalamus and cortex only in terms of gross statistical parameters of their interconnection, and then asked if certain aspects such as cortical rhythms could be explained on this basis. In this case one only wants some crude parameters of overall system behaviour such as the period of rhythm recorded in gross potentials, and so one can "average out" a lot of detail by statistical mechanical techniques. But if one wants to look at the detailed state-dependent processing of inputs to get outputs then one has to impose far more structure, and study deterministic operation at a certain level.

Another approach to modelling a large system is that of compartment models. A brain modeller taking such an approach will not try to average over the complete system, but will look at the gross anatomy of the brain to subdivide the brain into various regions. lle will thus try to simplify the problems of explaining one large region of the brain by breaking it down into a collection of interconnected "black boxes" and see if by making multiple plausible guesses about those boxes and their interconnections he can put together a reasonably functional model of the overall system. It may then be easier to take those individual boxes with their plausible functions and try to model them back down to the cellular level than trying to do the whole thing directly. Perhaps one of the most interesting brain models of this kind is that of Kilmer, McCulloch and Blum [1968] on the reticular formation. They looked at the neuroanatomy and saw that the formation could be viewed as a series of "modules" ascending the longitudinal axis. Each module could then be modeled as a whole, and then the simulacra could be interconnected to get the overall changeof-mode behavior which they posit to be exhibited by the reticular formation.

With this as background, I want to suggest eight principles which may help us understand how the human brain can control the complexities of a human's behaviour. (Their elaboration will appear in my forthcoming book "The Metaphorical Brain"):

Many of the ideas in the rest of this section were developed in Arbib [1971] on the basis of work by Arbib, Dev and Didday (see also, Arbib, Dev and Didday [1971] and Didday [1971 a,b]).

1. Theory Must be Action-Oriented:

One often talks as if human perception merely involved being able, when shown an object, to respond by naming it correctly. However, it is often more appropriate to say of an animal that it perceives its environment to the extent that it can interact appropriately with that environment. We can perceive a cat by naming it, true, but our perception may involve no conscious awareness of its being a cat per se, as when it jumps on our lap while we are reading and we simply classify it by the action we take as "something-to-be-stroked" or "something-to-be-pushed-off". In computer jargon, then, we may say that perception of an object generally involves the gaining of access to "programs" for controlling interaction with the object, rather than simply generating a "label" for the object.

2. Redundancy of Potential Command:

We were careful to characterize perception as a gaining of access to a program rather than the execution of a program - you perceive something and yet may still leave it alone. Thus in gaining access to the program, the system only gives it potential command, further processing being required to determine whether or not to act. A key question will thus be "How is the central nervous system structured to allow coordinated action of the whole animal when different regions receive contradictory local information?" McCulloch suggested that the answer lay in the Principle of Redundancy of Potential Command which states, essentially, that command should pass to the region with the most important information. He cited the example of the behavior of a World War I naval fleet controlled - at least temporarily - by the signals from whichever ship first sighted the enemy, the point being that this ship need not be the flagship, in which command normally resided.

McCulloch further suggested that this redundancy of potential command in vertebrates would find its clearest expression in the reticular formation of the brain stem (RF). Kilmer and McCulloch then made the following observations towards building a model of RF:

- (i) They noted that at any one time an animal is in only one of some 20 or so gross modes of behavior sleeping, eating, grooming, mating, urinating, for example and posited that the main role of the core of the RF (or at least the role they sought to model) was to commit the organism to one of these modes.
- (ii) They noted that anatomical data of the Scheibels [1958] suggested that RF need not be modelled neuron by neuron, but could instead be considered as a stack of "poker chips," each containing tens of thousands of neurons, and each with its own nexus of sensory information.
- (iii) They posited that each module ("poker chip") could decide which mode was most appropriate to its own nexus of information, and then asked, "How can the modules be coupled so that, in real-time, a consensus can be reached as to the mode appropriate to the overall sensory input, despite conflicting mode indications from local inputs to different modules?"

This was the framework within which Kilmer, McCulloch and Blum [1968] designed and simulated the compartment model, called S-RETIC, which we have discussed above of a system to compute mode changes, comprising a column of modules which differed only in their input array, and which were interconnected in a way suggested by RF anatomy.

Another useful system for the study of redundancy of potential command is the frog, which is normally immobile, but will snap at any

fly that comes into suitable range - "snapping" comprising a movement of the head (and, when necessary, the body) to aim at the fly and the rapid extension of the tongue to "zap" the fly. The situation seems very simple in that the frog does not seem to recognize flies as such - rather it will snap at any wiggling object, but will not snap at a stationary (i.e. dead) fly. A frog confronted with two flies then presents us with a beautifully simple redundant command situation - normally the animal snaps at one of the flies, and so we have sought to model the brain mechanism that determines which of the flies will "take command" of the frog.

Lettvin, Maturana, McCulloch and Pitts (1959) found that most ganglion cells of the frog's retina could be classified as being one of four types - such as "moving spot detectors" and "large moving object detectors". Incidentally, none of these are found in the cat, whose retinal ganglion cells may better be characterized as "contrast enhancement devices". This ties in with our first action-oriented point of view - a frog with little visually-guided behaviour beyond snapping at "wiggles" and jumping away from "enemies" has a retina which "throws away" most aspects of the visual input not related to these features, whereas a cat, leading a subtle life (such as watching a mousehole intently, and only springing when the mouse pokes his head out far enough) cannot function with so specialized a retina.

To get to our third point, however, what we want to emphasize is the way in which the information from the four types of detectors is distributed in the brain. Their axons terminate (among other places) in a brain structure called the <u>tectum</u>, with the terminations forming four separate layers, one atop each other, with the properties that (a) different layers correspond to different types of detector; (b) each

layer preserves the spatial relations between the original cells (i.e. there exists a direction along the layer corresponding to moving across the retina); (c) that terminations stacked above one another in the four layers come from ganglion cells with overlapping receptive fields. This is another dramatic case of the neural specificity we have discussed in Section 2 (see also Sperry [1951]). Such a relationship between two layers of cells - in this case the retina and any of the four tectal layers - is called somatotopic, from the Greek soma (body) and topos (place), since it preserves information about place on the body as we move from receptors to the central nervous system. We thus state our third principle, known to all neuroanatomists, which has been strangely neglected in brain theory:

3. The Brain "is" a Layered Somatotopic Computer:

It should be noted that somatotopy may preserve rough spatial relationships (up and down versus across), but does not preserve relative sizes. For example, in the layer in the human brain which receives touch information from the body, the fingers occupy a larger area than the trunk, since the brain needs detailed sensory information from the fingers if it is to control fine manipulation. Actually, our third principle is too strong, but is certainly useful for resolving many problems, for in view of the amazing specificity in retino-tectal connections and the unmodifiable motor apparatus of the salamander we may find it very hard to believe that further from the periphery chaos takes over to yield a "completely" random network. I suggest that we look at the brain in terms of specific structures, and only use randomization when we really feel we are ignorant. In other words, it is a justified strategy to make a model in which only certain parameters can be confidently specified - either by experiment or previous theory -

and thus to set up random values for all the other parameters in the model. One may hopefully explain some of the functions for the system being modeled despite our gap of knowledge about structure, and then gain more detailed understanding of other functions as we find out more about further details of structure. This is something of an evolutionary strategy of biological modelling. What our third principle says is that a useful way to structure the apparent chaos of many parts of the brain is to describe such parts in terms of interconnected layers, where position within the layer is a crucial indicator of the functional significance of a cell's activity, and where an analysis of one patch of such a layer may yield an understanding of the function of the layer as a whole. We must add that muscles are not unitary devices with a single controller, but instead each muscle comprises a multitude of fibres controlled by a whole population of neurons. Since an array of input cells must thus control, with the aid of internal variables, an array of output cells, it seems at least plausible that it is an array, rather than a central executive, that intervenes. We thus make the hypothesis that, unlike most digital computers,

4. The Brain is a Distributed, Highly Parallel Computer

Our next point has been well introduced by our discussion of Section 2, which we may augment by suggesting that certain vagaries of brain structure only make sense when we see that the human brain is a variation on an evolutionary theme - and herein lies much of the power of comparative studies which use experiments on animal brains to help unravel the knot of human mentation. Similarly, we must note that the brain had to grow, rather than being wired-up by a technician who could refer item by item to a blueprint. Thus in explaining organismic behaviour we must stress that:

5. Brains have Evolved; Further each Brain has Grown:

Evolution has given each animal a basic repertoire of skills for survival. The frog brain enables the frog to snap at flies; the human brain enables the human newborn to suck and gaze and breathe and excrete. But in all animals to some extent, more so in mammals and perhaps exceptionally so in man, these evolutionary skills are augmented by individually acquired skills and memories. The social basis for much of human skills is, in fact, so great that nowadays man's adaptation of and to his environment is more dramatically a process of cultural than of biological evolution. These experiences, skills, memories cohere into what has been called an internal model of the world. This model is not a cardboard replica, but rather the memory structure that, for example, lets us walk into a strange room and, on the basis of visual stimuli from a brownish rhombus, know that a table is present and that we may put the papers we are carrying on that table without risk that they will fall to the floor. Thus:

6. The Brain must be able to Correlate Sensory Data and Actions in such a Way as to Build up an Internal Model of the World.

Of course it is not enough to perceive the presence of a table on which we place our papers if we then release our grasp of them some three feet from the table. Too many discussions of perception overlook our first point (action orientation) and so talk as if it were enough to classify an object. But we must know where it is if we are to interact with it:

7. Perception is of Where as well as of What

Finally, we note that when walking around obstacles, we decide where to walk but, unless the ground is very even, need not concentrate

on placing our footsteps; further, it appears that the midbrain control of stepping can relegate to spinal mechanisms the maintenance of an upright posture as we step. These, and other, considerations will suggest that it is useful to theorize that

8. Both Structurally and Functionally, the Brain is Heirarchically Organized.

To briefly point up these principles, let us close with a discussion of a model of frog behaviour. Pitts and McCulloch, [1947] offered a model of the superior colliculus (which is the equivalent of the tectum in the cat) which gave a plausible explanation of how an animal might fixate its gaze at the "average" or "centre of gravity" of a field of illumination. For us, their scheme has the added significance that it showed how to design a somatotopically organized network in which there is no "executive neuron" which decrees which way the overall system behaves - rather the dynamics of the effectors, with assistance from neuronal interactions, extracts the output trajectory from a population of neurons, none of which has more than local information as to which way the system should behave.

If we paraphrase our interpretation of the significance of the Pitts and McCulloch model of the superior colliculus to say that it showed how "the organism can be committed to an overall action by a population of motoneurons none of which had global information as to which action is appropriate, "we are struck by the similarity of the situation to that in our statement of the RF problem.

As mentioned earlier,# several flies are within the "snapping zone" of a frog, the frog will usually snap at one of them. Though this could be explained in terms of a serial scan made of the tectum

until a region is first found in which the activity in the four layers signals the presence of a fly - at which stage the scanner would issue a command to snap in the direction indicated by the current address of the scan-one may argue that such serial processing is not a candidate for the frog's neural machinery because of the fact that the frog will sometimes snap midway between two flies - precisely the "center of gravity" effect one expects from an output system of the distributed computation type suggested by Pitts and McCulloch for centering of gaze.

Noting that the above distinction between serial and distributed processing could not be made by asking only the usual question of sensory physiology, "What information is relayed to the brain?" but by also asking, "How does the animal make use of such information to act?" we see again the importance of our first principle. Some insightful answers to the latter question for the frog have been generated by Richard Didday in his 1970 Ph.D. thesis from Stanford - portions of which appear in Didday [1971 a,b]

The second principle is reaffirmed when we note that while the Pitts-McCulloch model does yield integrated behavior, it does not explain the "usually-one-fly-effect." It turns out that the mechanism for this bears a great resemblance to the Kilmer-McCulloch RF model.

The observations on frog behavior suggest three layers of processing, each involving distributed computation. The first layer operates upon the four layers of retinal information to provide for each region a measure of "foodness." The third layer does a modified Pitts-McCulloch type computation to direct motion of the frog to the position corresponding to the "center of gravity" of activity in the second layer. The task of the second layer is then very much akin to the task of the Kilmer-

McCulloch RF. Where that model has an array of modules which must interact to get a majority favoring the same mode, the task of the second layer of our hypothetical tectum is to turn down the activity of all but one region of (or from) the first layer. The essential mechanisms turn out to be very similar, and provide an explanation for the "sameness" and "newness" neurons observed by Lettvin et al. The models differ in having all modes evaluated in each module, versus having a module identified with a mode. In any case, the study of frog behavior sheds new insight on RF modelling, and suggests alternate hypotheses. Our model is still a crude oversimplification of the complexities of a real frog brain, but we believe that our partial successes show that our organizational principles, all too often neglected in the cybernetics literature, must play a crucial role in future brain theory.

References

- P. K. Anokhin, Systemogenesis as a General Regulator of Brain Development, in 'The Developing Brain' (W. A. and H.E. Himwich, Eds.) Progress in Brain Research 9 (1964) 54-86.
- M. J. Apter (1966) "Cybernetics and Development", Oxford: Pergaman Press.
- M. A. Arbib (1967) "Automata Theory and Development, I;" J. Theoret Biol., 14, 131-156.
- M. A. Arbib (1971) "How We Know Universals: Retrospect and Prospect," Mathematical Biosciences.
- M. A. Arbib, P. Dev and R. L. Didday (1971) "Organization of an Action-Oriented Memory for a Perceiving System," Journal of Cybernetics $\underline{1}$ (in 2 parts).
- P. C. Baker and T. E. Schroeder (1967) "Cytoplasmic Filaments and Morphogenetic Movement in the Amphibian Neural Tube," Developmental Biology, 15, 432-450.
- C. M. Child (1941) "Patterns and Problems of Development", Chicago: Univ. of Chicago Press.
- J. D. Cowan (1969) "Statistical Mechanics of Nervous Activity," Technical Report JDC 69-1, Committee on Mathematical Biology, University of Chicago.
- R. L. Didday (1971 a) "An Easy Method for Simulating Distributed Computation in Nervous Systems," Int'l J. of Man Machine Systems. (in press)
- R. L. Didday (1971 b) "A Possible Decision-Making Role for the 'Sameness' and 'Newness' Cells in the Frog," submitted to Brain Behav. and Evol.
- D. A. Ede (1971) "Cell Behaviour and Embryonic Development", these Proceedings.
- D. A. Ede and G. S. Agerbak (1968) "Cell Adhesion and Movement in Relation to the Developing Limb Pattern in Normal and <u>Talpid</u> Mutant Chick Embryos." J. Embryol. Exp. Morph. 20, 81-100.
- D. A. Ede and J. T. Law (1969) "Computer Simulation of Vertebrate Limb Morphogenesis," Nature, 221, 244-248.
- B. C. Goodwin and N. H. Cohen (1969) "A Phase-Shift Model for the Spatial and Temporal Organization of Developing Systems," J. Theoret Biol. 25, 49.
- T. Gustafson and L. Wolpert (1967) "Cellular Movement and Contact in Sea Urchin Morphogenesis," Biological Reviews, 42, 442-498.

- W. L. Kilmer, W. S. McCulloch and J. Blum (1968): "Some Mechanisms for a Theory of the Reticular Formation," in Systems Theory and Biology (M. Mesarović, Ed.), New York: Springer-Verlag, 286-375.
- R. Laing (1969) "Formalisms for Living Systems," University of Michigan Report 08226-8-T.
- R. Laing (1971) "Formalisms for Biology: A Hierarchy of Developmental Processes", these Proceedings.
- J. Y. Lettvin, H. R. Maturana, W. S. McCulloch and W. H. Pitts (1959): "What the Frog's Eye Tells the Frog's Brain," Proc. IRE, 47, 1950-1959.
- A. Lindenmayer (1968) "Mathematical Models for Cellular Interactions in Development," J. Theoret. Biol. <u>18</u>, 280-299, 300-315.
- W. H. Pitts and W. S. McCulloch (1947): "How We Know Universals: The Perception of Auditory and Visual Forms," Bull. Math. Biophys., 9, 127-147.
- A. B. Scheibel and M. E. Scheibel (1958): "Structural Substrates for Integrative Patterns in the Brain Stem Reticular Core," in Reticular Formation of the Brain (II. II. Jasper et al., Eds.), Boston: Little, Brown, 31-55.
- T. E. Schroeder (1970) "Neurulation in <u>Xenopus Laevis</u>. An Analysis and Model Based Upon Light and Electron Microscopy" J. Embryol. exp. Morphol. 23, 427-462.
- T. E. Schroeder (1971) "Mechanisms of Morphogenesis: The Embryonic Neural Tube," these Proceedings.
- R. W. Sperry (1951) "Mechanisms of Neural Maturation," in Handbook of Experimental Psychology, New York: John Wiley, 236-280.
- J. P. Trinkaus (1969) "Cells Into Organs: The Forces that Shape the Embryo," Englewood-Cliffs, N.J.: Prentice-Hall.
- J. vonNeumann (1966) "Theory of Self-Reproducing Automata," U. of Illinois Press (edited and completed by A. W. Burks).
- P. A. Weiss (1941) "Self-Differentiation of the Basic Patterns of Coordination," Comp. Psychol. Monogr. 17, 1-96.
- D. M. Wilson (1966) "Insect Walking", Ann. Rev. Entom. 11, 103-122.
- S. Winograd and J. D. Cowan (1963) "Reliable Computation in the Presence of Noise," Cambridge, Mass. The MIT Press.
- L. Wolpert (1969) "Positional Information and the Spatial Pattern of Cellular Differentiation," J. Theoret. Biol. <u>25</u>, 1-47.
- L. Wolpert and T. Gustafson (1967) "Cell Movement and Cell Contact in Sea Urchin Morphogenesis," Endeavour, 26, No. 98 (May) 85-90.