# Stochastic Differential Equations for Power Law Behaviors

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### Abstract

We present in this paper some simple stochastic differential equations that leads to lower-tail and/or upper tail power law behaviors. We also present a model with bi-directional Poisson counters that exhibits power law behavior near a critical point, which might be of interest to statistical physics.

### I. INTRODUCTION

As has been observed many times in recent years, empirical studies dealing with a variety of subject matter produce data showing power law histograms extending over several decades or more. The diversity of application areas, and the extent of the data have inspired researchers to look for general principles that would make it possible to trace the individual phenomena back one or more common features. Among recent work along these lines we call attention to [1], [3], [4], [5]. In this paper we pursue the idea that certain simple forms of first order stochastic differential equations have steady state densities which show lower tail or upper tail power law behavior, depending on the values of the parameters. To the extent that the form and parameters of a differential equations are often more readily identified in the modeling process, the differential equations we describe may be thought of as providing a more direct explanation of power law behavior.

In their interesting paper [5], Reed and Hughes consider the probability density of the value of a growing exponential sampled at a exponentially distributed random time. As they observe, this is easily seen to give a power law distribution. Here we consider a different situation involving the steady state density associated with a stochastic differential equation. The equation describes a situation in which the quantity of interest decays to zero following an exponential,  $\dot{X} = -\alpha X$ , but is incremented by a fixed amount  $\sigma$  at random times, the times having an exponential distribution. We show that for a range of parameter values the steady state distribution of X exhibits a power law lower tail. The fact that we deal with the steady state property of an ongoing dynamics gives our work a different set of possibilities for interpretation. The basic reason as to why the distribution of values in steady state has the same form as the distribution of values obtained by sampling at a random time, lies in the form of the drift term associated with the differential equation.

When considering lower tail behavior, we find it useful to distinguish between what might be called "two sided" lower tails and "one sided" lower tails. The latter may occur when dealing with an intrinsically nonnegative quantity, such as queue length whereas the former might apply in a situation in which the histogram extends in both directions from a critical value, as might be the situation for some types of populations near a phase transition. Our models for one sided lower tail behavior focuses on the steady state behavior associated with stochastic differential equations containing a Poisson counter N and taking the form

$$\mathrm{d}X = f(X)\mathrm{d}t + g(X)\mathrm{d}N.$$

For two sided lower tails we consider slightly more complicated models of the form

$$\mathrm{d}X = f(X)\mathrm{d}t + g_1(X)\mathrm{d}N_1 - g_2(X)\mathrm{d}N_2.$$

We also study the more popular case of upper tail power law. A simple transformation is shown to convert one sided lower tail power laws into upper tail power laws. In view of dynamic systems, evolutions of this type can also give generative interpretations of many power law upper tails observed in real data. In Section II we first present our motivating example of a simple Poisson counter driven SDE, the steady-state distribution of which was shown by Brockett [1] to exhibit power law behavior near the origin. We then introduce a simple transformation to develop a similar SDE that leads to an upper tail power law. We observe that various distributions can be generated via simple modifications of the "drift term" in the SDE. In Section III, we add a Brownian motion term to obtain a similar result as Reed [4]. All of these cases demonstrate that "random multiplication with exponential stopping time will lead to power law behaviors". In Section IV we develop an SDE driven by Poisson counters in both positive and negative directions. We show that the steady-state distribution can exhibit power law behavior near a critical point. This may have implications in statistical physics since a discontinuity occurs in a surprising way. Section V concludes the paper.

## II. SDE DRIVEN BY A POISSON COUNTER

The following SDE was considered by Brockett [1],

$$\mathbf{d}X_t = -\alpha X_t \mathbf{d}t + \sigma \mathbf{d}N_t \tag{1}$$

where  $\alpha, \sigma > 0$  and N is a Poisson process of intensity  $\lambda$ . By Theorem 6.2 in [2], there is a unique adapted RCLL process  $\{X_t\}$  satisfying (1) and

$$\sup_{t \in [0,T]} \mathbb{E}[X_t^2] < \infty \tag{2}$$

for any  $T \in [0, \infty)$ . Similar arguments for the existence of solutions apply to all the other SDE's considered in this paper and will not be repeated.

Now let  $\psi_k(x) = e^{ikx}$ . By Itô's formula,

$$d\psi_k(X_t) = -i\alpha k X_t \psi_k(X_t) dt + [\psi_k(X_{t-} + \sigma) - \psi_k(X_{t-})] dN_t$$
$$= -\alpha k \frac{\partial \psi_k(X_t)}{\partial k} dt + (e^{ik\sigma} - 1)\psi_k(X_{t-}) dN_t$$

Taking expectation,

$$\frac{\partial}{\partial t}\Phi_X(k,t) = -\alpha k \frac{\partial}{\partial k}\Phi_X(k,t) + \lambda(e^{ik\sigma} - 1)\Phi_X(k,t)$$
(3)

where  $\Phi_X(k,t) = \mathbb{E}(\psi_k(X_t))$  is the characteristic function of  $X_t$  and the change of the order of differentiation and expectation can be justified by (2) and Lebesgue's Dominated Convergence Theorem. (3) can be solved by the method of characteristics to yield

$$\Phi_X(k,t) = \Phi_X(ke^{-\alpha t},0) \exp\left\{\lambda \int_0^t \left[\exp\left(ik\sigma e^{\alpha(s-t)}\right) - 1\right] \mathrm{d}s\right\}$$
(4)

After a change of variable  $u = \sigma \exp(\alpha(s - t))$ , (4) becomes

$$\Phi_X(k,t) = \Phi_X(ke^{-\alpha t},0) \exp\left\{\frac{\lambda}{\alpha} \int_{\sigma e^{-\alpha t}}^{\sigma} \frac{e^{iku} - 1}{u} \mathrm{d}u\right\}$$
(5)

yielding

$$\Phi_X(k,\infty) = \exp\left\{\frac{\lambda}{\alpha}\int_0^\sigma \frac{e^{iku}-1}{u}\mathrm{d}u\right\}$$

By Lemma 2 of [6], the steady-state distribution is absolutely continuous and the density is continuous if and only if  $\lambda > \alpha$ .

Note that  $\Phi_X(k,\infty)$  satisfies the following equation, obtained from (3) by setting the right-hand side to zero,

$$-\alpha k \frac{\mathrm{d}}{\mathrm{d}k} \Phi(k) + \lambda (e^{ik\sigma} - 1) \Phi(k) = 0$$

Thus the corresponding density  $f_X(x)$  satisfies

$$\alpha \frac{\mathrm{d}}{\mathrm{d}x} [xf(x)] + \lambda f(x - \sigma) - \lambda f(x) = 0 \tag{6}$$

It was shown in [7] that  $f_X(x) = 0$  for x < 0. We can arrive at the same conclusion in a more intuitive way by examining (1). Indeed, note that X will eventually become positive and remain so from that point on. Now using  $f_X(x) = 0$  for  $x \le 0$ , (6) can be solved recursively to give

$$f_X(x) = \begin{cases} 0, & x \in (-\infty, 0] \\ Cx^{\frac{\lambda}{\alpha} - 1}, & x \in (0, \sigma] \\ f_X(n\sigma) \left(\frac{x}{n\sigma}\right)^{\frac{\lambda}{\alpha} - 1} - \frac{\lambda}{\alpha} x^{\frac{\lambda}{\alpha} - 1} \int_{n\sigma}^x u^{-\frac{\lambda}{\alpha}} f_X(u - \sigma) \mathrm{d}u, & x \in (n\sigma, n\sigma + \sigma], n \ge 1 \end{cases}$$

where the constant C is determined by the normalization condition

$$\int_{-\infty}^{\infty} f_X(x) \mathrm{d}x = 1$$

Note that  $f_X(x)$  has a power law at its lower tail.

We briefly mention that (1) can have the following generalization,

$$\mathrm{d}X_t = AX_t\mathrm{d}t + b\mathrm{d}N_t$$

where X is an  $\mathbb{R}^n$ -valued process, A an  $n \times n$  stable matrix and  $b \in \mathbb{R}^n$ . Then the steady-state distribution has the following characteristic function

$$\Phi_X(k,\infty) = \exp\left\{\lambda \int_0^\infty \left[\exp\left(ik^T e^{As}b\right) - 1\right] \mathrm{d}s\right\}$$

where  $k \in \mathbb{R}^n$ , and the projection of X onto a left eigenvector of A exhibits power law near the origin.

Now we introduce the simple transformation  $Y_t = X_t^{-1}$  to convert the lower tail power law into an upper tail power law. For  $y \ge \varepsilon \triangleq \sigma^{-1}$ , the steady-state density of Y is

$$f_Y(y) = f_X(y^{-1})y^{-2} = Cy^{-\frac{\lambda}{\alpha}-1}, \quad y \in [\varepsilon, \infty)$$

Using Itô's formula, we can get the equation governing the evolution of  $Y_t$ ,

$$dY_t = \alpha Y_t dt - \frac{Y_{t-}^2}{\varepsilon + Y_{t-}} dN_t$$
(7)

Note that at each jumping point, Y drops to  $\frac{Y_{t-}}{\varepsilon+Y_{t-}}$ , which is smaller than one and can be arbitrarily close to zero. We can modify the coefficient in front of  $dN_t$  in (7) so that it always restores the process to a fixed point. The

We can modify the coefficient in front of  $dN_t$  in (7) so that it always restores the process to a fixed point. The equation then becomes

$$dZ_t = \alpha Z_t dt + (z_0 - Z_{t-}) dN_t$$
(8)

with the corresponding equation for the characteristic function  $\Phi_Z(k,t)$  of  $Z_t$  being

$$\frac{\partial}{\partial t}\Phi_Z(k,t) = \alpha k \frac{\partial}{\partial k}\Phi_Z(k,t) - \lambda \Phi_Z(k,t) + \lambda e^{ikz_0}$$
(9)

(9) can be solved again by the method of characteristics, yielding

$$\Phi_Z(k,t) = e^{-\lambda t} \Phi_Z(ke^{\alpha t},0) + \lambda \int_0^t \exp\left\{\lambda(s-t) + iz_0 ke^{\alpha(t-s)}\right\} ds$$
(10)

After a change of variable  $z = z_0 e^{\alpha(t-s)}$ , (10) becomes

$$\Phi_Z(k,t) = e^{-\lambda t} \Phi_Z(ke^{\alpha t},0) + \frac{\lambda}{\alpha z_0} \int_{z_0}^{z_0 e^{\alpha t}} \left(\frac{x}{z_0}\right)^{-\frac{\lambda}{\alpha}-1} e^{ikx} dx$$

from which we can read off the distribution function,

$$F_Z(z,t) = e^{-\lambda t} F_Z(ze^{-\alpha t}, 0) + (1 - e^{-\lambda t})G(z,t)$$

where G(z, t) is a truncated Pareto distribution,

$$G(z,t) = \begin{cases} 0, & z < z_0\\ (1 - e^{-\lambda t})^{-1} \left( 1 - \left(\frac{z}{z_0}\right)^{-\frac{\lambda}{\alpha}} \right), & z \le z_0 \le z_0 e^{\alpha t}\\ 1, & z > z_0 e^{-\alpha t} \end{cases}$$

As  $t \to \infty$ , the distribution  $F_Z(z,t)$  approaches a Pareto distribution

$$F_Z(z,\infty) = 1 - \left(\frac{z}{z_0}\right)^{-\frac{\lambda}{\alpha}}, \quad z \ge z_0.$$

A closely related model of deterministic exponential growth with exponential stopping time was analyzed in [5]. We note by passing that the proportional growth is critical in generating power law. Had the growth term in (8) been  $\alpha Z_t^{\delta} dt$  for some  $\delta \in [0, 1)$ , the resulting distribution would have been Weibull with distribution function

$$F_Z(z,\infty) = 1 - \exp\left\{-\frac{\lambda}{\alpha(1-\delta)}(z^{1-\delta} - z_0^{1-\delta})\right\}, \quad z \ge z_0$$

#### III. SDE DRIVEN BY BOTH BROWNIAN MOTION AND POISSON COUNTER

In this section, we add a Brownian motion component to (8), which becomes

$$dX_t = \mu X_t dt + \sigma X_t dW_t + (x_0 - X_{t-}) dN_t$$
(11)

where  $\mu, x_0 \in \mathbb{R}, \sigma > 0$ , W is a standard Brownian motion and N is a Poisson process with density  $\lambda$ , independent of W. This is a geometric Brownian motion with Poisson jumps which always reset the motion to a fixed state  $x_0$ . A similar model was analyzed in Reed [4].

Let  $Y_t = \log X_t$  and  $y_0 = \log x_0$ . Then Itô's formula gives

$$\mathrm{d}Y_t = \left(\mu - \frac{1}{2}\sigma^2\right)\mathrm{d}t + \sigma\mathrm{d}W_t + (y_0 - Y_{t-})\mathrm{d}N_t$$

which is a Brownian motion randomly reset to  $y_0$  by Poisson jumps. Let  $\psi_k(y) = e^{iky}$  as in the previous section. By Itô's formula,

$$d\psi_k(Y_t) = ik\psi_k(Y_t) \left[ \left( \mu - \frac{1}{2}\sigma^2 \right) dt + \sigma dW_t \right] - \frac{1}{2}\sigma^2 k^2 \psi_k(Y_t) dt + (e^{iky_0} - \psi_k(Y_{t-1})) dN_t$$

Taking expectations, we get

$$\frac{\partial}{\partial t}\Phi_Y(k,t) = \left[i\left(\mu - \frac{1}{2}\sigma^2\right)k - \frac{1}{2}\sigma^2k^2 - \lambda\right]\Phi_Y(k,t) + \lambda e^{iky_0}$$

where  $\Phi_Y(k,t)$  is the characteristic function of  $Y_t$ . The solution is

$$\Phi_Y(k,t) = \Phi_Y(k,\infty) + e^{-\lambda t} [\Phi_Y(k,0) - \Phi_Y(k,\infty)] e^{i(\mu t - \frac{1}{2}\sigma^2 t)k - \frac{1}{2}\sigma^2 tk^2}$$

where

$$\Phi_Y(k,\infty) = \frac{-\lambda e^{iky_0}}{i(\mu - \frac{1}{2}\sigma^2)k - \frac{1}{2}\sigma^2k^2 - \lambda}$$

Now we can find the steady-state density of  $Y_t$  as  $t \to \infty$  by taking the inverse Fourier transform of  $\Phi_Y(k, \infty)$ ,

$$f_Y(y) = \begin{cases} \frac{\alpha\beta}{\alpha+\beta} e^{\beta(y-y_0)}, & y \le y_0\\ \frac{\alpha\beta}{\alpha+\beta} e^{-\alpha(y-y_0)}, & y \ge y_0 \end{cases}$$

where  $\alpha > 0$  and  $-\beta < 0$  are the two roots of the following quadratic equation,

$$\frac{1}{2}\sigma^2\gamma^2 + \left(\mu - \frac{1}{2}\sigma^2\right)\gamma - \lambda = 0 \tag{12}$$

Going back to X, we get the steady-state density of  $X_t$  as  $t \to \infty$ 

$$f_X(x) = f_Y(\log x)x^{-1} = \begin{cases} x_0^{-1} \frac{\alpha\beta}{\alpha+\beta} \left(\frac{x}{x_0}\right)^{\beta-1}, & x \in (0, x_0] \\ x_0^{-1} \frac{\alpha\beta}{\alpha+\beta} \left(\frac{x}{x_0}\right)^{-\alpha-1}, & x \in [x_0, \infty) \end{cases}$$
(13)

which is the double Pareto distribution of Reed [4].

Motivated by the connection between (7) and (8), we also consider the following SDE

$$dZ_t = \mu Z_t dt + \sigma Z_t dW_t - \frac{Z_{t-}^2}{Z_{t-} + \varepsilon} dN_t$$
(14)

with  $Z_0 > 0$ . Let  $U_t = Z_t^{-1}$ . Then

$$\mathrm{d}U_t = -(\mu - \sigma^2)U_t\mathrm{d}t - \sigma U_t\mathrm{d}W_t + \varepsilon^{-1}\mathrm{d}N_t$$

By the same procedure as before, we get the equation for the characteristic function  $\Phi_U(k,t)$  of U,

$$\frac{\partial}{\partial t}\Phi_U(k,t) = -(\mu - \sigma^2)k\frac{\partial}{\partial k}\Phi_U(k,t) + \frac{1}{2}\sigma^2k^2\frac{\partial^2}{\partial k^2}\Phi_U(k,t) + (e^{ik/\varepsilon} - 1)\Phi_U(k,t)$$

which is the Fourier transform with respect to the variable y of the following Fokker-Planck equation for the density  $f_Y(y,t)$  of  $Y_t$ ,

$$\frac{\partial}{\partial t}f_Y(y,t) = (\mu - \sigma^2)\frac{\partial}{\partial y}[yf_Y(y,t)] + \frac{1}{2}\sigma^2\frac{\partial^2}{\partial y^2}[y^2f_Y(y,t)] + \lambda f_Y(y - \varepsilon^{-1},t) - \lambda f_Y(y,t)]$$

In steady state, the density  $f_Y(y)$  satisfies

$$(\mu - \sigma^2) \frac{d}{dy} [y f_Y(y)] + \frac{1}{2} \sigma^2 \frac{d^2}{dy^2} [y^2 f_Y(y)] + \lambda f_Y(y - \varepsilon^{-1}) - \lambda f_Y(y) = 0$$

For  $y \in (0, \varepsilon^{-1}]$ , this reduces to

$$(\mu - \sigma^2) \frac{\mathrm{d}}{\mathrm{d}y} [y f_Y(y)] + \frac{1}{2} \sigma^2 \frac{\mathrm{d}^2}{\mathrm{d}y^2} [y^2 f_Y(y)] - \lambda f_Y(y) = 0$$
(15)

The general solution to (15) is given by

$$f_Y(y) = Cy^{\alpha - 1} + Dy^{-\beta - 1}, \quad y \in (0, \varepsilon^{-1}]$$

where  $\alpha$  and  $\beta$  are as in (13). The integrability of  $f_Y(y)$  requires that D = 0, so

$$f_Y(y) = Cy^{\alpha - 1}, \quad y \in (0, \varepsilon^{-1}]$$

Therefore,

$$f_X(x) = f_Y(x^{-1})x^{-2} = Cx^{-\alpha - 1}, \quad x \in [\varepsilon, \infty)$$

which has the same upper tail power law exponent as in (13). This is intuitive since the difference of the two models lies in the range of small x.

## IV. SDE DRIVEN BY BI-DIRECTIONAL POISSON COUNTERS

In this section, we consider the following SDE driven by bi-directional Poisson counters,

$$\mathrm{d}X_t = \alpha(\mu - X_t)\mathrm{d}t + \sigma_1\mathrm{d}P_t - \sigma_2\mathrm{d}N_t$$

where  $\mu \in \mathbb{R}$ ,  $\alpha, \sigma_1, \sigma_2 > 0$ , and P, N are two independent Poisson processes with intensities  $\lambda_1, \lambda_2$ , respectively. By a simple shift of the origin, we may assume without loss of generality that  $\mu = 0$  and the equation then becomes

$$dX_t = -\alpha X_t dt + \sigma_1 dP_t - \sigma_2 dN_t \tag{16}$$

The characteristic function  $\Phi_X(k,t)$  satisfies the following equation,

$$\frac{\partial}{\partial t}\Phi_X(k,t) = -\alpha k \frac{\partial}{\partial k}\Phi_X(k,t) + \left[\lambda_1(e^{ik\sigma_1}-1) + \lambda_2(e^{-ik\sigma_2}-1)\right]\Phi_X(k,t)$$
(17)

the solution of which is

$$\Phi_X(k,t) = \Phi_X(ke^{-\alpha t},0) \exp\left\{\frac{\lambda_1}{\alpha} \int_{\sigma_1 e^{-\alpha t}}^{\sigma_1} \frac{e^{ik\sigma_1} - 1}{u} du - \frac{\lambda_2}{\alpha} \int_{-\sigma_2}^{-\sigma_2 e^{-\alpha t}} \frac{e^{ik\sigma_2} - 1}{u} du\right\}$$

Therefore,

$$\Phi_X(k,\infty) = \exp\left\{\frac{\lambda_1}{\alpha}\int_0^{\sigma_1} \frac{e^{ik\sigma_1} - 1}{u}du - \frac{\lambda_2}{\alpha}\int_{-\sigma_2}^0 \frac{e^{ik\sigma_2} - 1}{u}du\right\}$$

Again Lemma 2 of [6] shows that  $\Phi_X(k,\infty)$  is the characteristic function belonging to an absolutely continuous distribution and the density is continuous if and only if  $\lambda_1 + \lambda_2 > \alpha$ . If  $\lambda_1 = \lambda_2 = \lambda$  and  $\sigma_1 = \sigma_2 = \sigma$ , the steadystate distribution will be symmetric around the origin. If, in addition,  $\sigma = \sigma_0 \lambda^{-\frac{1}{2}}$ , then as  $\lambda \to \infty$ , (16) converges to the Ornstein-Uhlenbeck process and

$$\Phi_X(k,\infty) \to \exp\left\{-\frac{\sigma_0^2}{2\alpha}k^2\right\}$$

i.e. the characteristic function of the normal distribution  $\mathcal{N}(0, \frac{\sigma_0^2}{\alpha})$  as expected. Setting the right-hand side of (17) to zero, we get the differential equation satisfied by  $\Phi_X(k, \infty)$ ,

$$-\alpha k \frac{\mathrm{d}}{\mathrm{d}k} \Phi_X(k,t) + \left[\lambda_1 (e^{ik\sigma_1} - 1) + \lambda_2 (e^{-ik\sigma_2} - 1)\right] \Phi_X(k,t) = 0$$

Thus the steady-state density satisfies the following equation,

$$\alpha \frac{\mathrm{d}}{\mathrm{d}x}[xf(x)] + \lambda_1 f(x - \sigma_1) - (\lambda_1 + \lambda_2)f(x) + \lambda_2 f(x + \sigma_2) = 0$$
(18)

Figure 1 on page 8 shows some steady-state densities for (16) obtained from simulation, where we have set  $\sigma_1 = \sigma_2 =$ 1 and  $\lambda_1 = \lambda_2$ . Note that as  $\frac{\lambda_1 + \lambda_2}{\alpha}$  becomes larger, the density becomes smoother, consistent with Lemma 2 of [6]. As  $\frac{\lambda_1 + \lambda_2}{\alpha}$  becomes smaller, the density becomes more sharply concentrated around zero. In the case  $\lambda_1 + \lambda_2 \ll \alpha$ ,  $f(x - \sigma_1)$  and  $f(x + \sigma_2)$  are negligible compared to f(x) for small x and hence (18) can be approximated by the following equation,

$$\alpha \frac{\mathrm{d}}{\mathrm{d}x} [xf(x)] - (\lambda_1 + \lambda_2)f(x) = 0$$

which can then be solved to give

$$f(x) = C|x|^{\frac{\lambda_1 + \lambda_2}{\alpha} - 1}, \quad 0 < |x| \ll 1$$

Figure 2 on page 8 plots the steady-state densities in log-log scale with the reference lines of slope  $\frac{\lambda_1 + \lambda_2}{\alpha} - 1$  superimposed. The approximation is very good near the origin.

This approximation can be made more rigorous. We will analyze the behavior of the density near the origin when  $\lambda_1 + \lambda_2 \leq \alpha$ . Let

$$\Phi_1(k) = \exp\left\{\frac{\lambda_1}{\alpha}\int_0^{\sigma_1} \frac{e^{ik\sigma_1} - 1}{u}du\right\}$$

and

$$\Phi_2(k) = \exp\left\{-\frac{\lambda_2}{\alpha}\int_{-\sigma_2}^0 \frac{e^{ik\sigma_2}-1}{u}du\right\}$$

which are the characteristic functions of two absolutely continuous distributions. Denote their densities by g(x) and h(x), respectively. Then [6] shows that g(x) has support on  $[0, \infty)$  and  $g(x) = Cx^{\frac{\lambda_1}{\alpha}-1}$  for  $x \in (0, \sigma_1]$ . Similarly, h(x) has support on  $(-\infty, 0]$  and  $h(x) = D|x|^{\frac{\lambda_2}{\alpha}-1}$  for  $x \in [-\sigma_2, 0)$ . Since  $\Phi_X(k, \infty) = \Phi_1(k)\Phi_2(k)$ , the density f(x) corresponding to  $\Phi_X(k, \infty)$  is given by

$$f(x) = \int_{-\infty}^{\infty} g(y)h(x-y)\mathrm{d}y$$

Let  $m = \min\{\sigma_1, \sigma_2\}$  and  $\epsilon \in (0, m)$ . For  $0 < x \le \sigma_1 - \epsilon$ , we have

$$\begin{split} f(x) &= \int_x^\infty g(y)h(x-y)\mathrm{d}y\\ &= \int_x^m Cy^{\frac{\lambda_1}{\alpha}-1}D(y-x)^{\frac{\lambda_2}{\alpha}-1}\mathrm{d}y + \int_m^\infty g(y)h(x-y)\mathrm{d}y\\ &= CDx^{\frac{\lambda_1+\lambda_2}{\alpha}-1}\int_1^{\frac{m}{x}}u^{\frac{\lambda_1}{\alpha}-1}(u-1)^{\frac{\lambda_2}{\alpha}-1}\mathrm{d}u + \int_m^\infty g(y)h(x-y)\mathrm{d}y\\ &= A_1x^{\frac{\lambda_1+\lambda_2}{\alpha}-1} + A_2 \end{split}$$

where  $A_1 = CD \int_1^{\frac{m}{x}} u^{\frac{\lambda_1}{\alpha}-1} (u-1)^{\frac{\lambda_2}{\alpha}-1} du$  and  $A_2 = \int_m^{\infty} g(y)h(x-y)dy$ . It is shown in [7] that g(x) is continuous on  $\mathbb{R} \setminus \{0\}$ . Since it is also integrable, it is uniformly bounded on  $[m, \infty)$  and hence

$$A_2 \leq \sup_{y \geq m} g(y) \int_m^\infty h(x-y) \mathrm{d}y \leq \sup_{y \geq m} g(y) < \infty$$

If  $\lambda_1 + \lambda_2 < \alpha$ , then

$$0 < CD \int_{1}^{\frac{\sigma_1}{\sigma_1 - \epsilon}} u^{\frac{\lambda_1}{\alpha} - 1} (u - 1)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u \le A_1 < CD \int_{1}^{\infty} u^{\frac{\lambda_1}{\alpha} - 1} (u - 1)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u < \infty$$

A similar analysis applies for the case  $x \in (-\sigma_2 + \epsilon, 0)$ . Therefore,

$$f(x) = \Theta\left(|x|^{\frac{\lambda_1 + \lambda_2}{\alpha} - 1}\right), \text{ as } x \to 0$$

If  $\lambda_1 + \lambda_2 = \alpha$ ,

$$A_1 = CD \int_1^{\frac{m}{x}} u^{\frac{\lambda_1}{\alpha} - 1} (u-1)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u \ge CD \int_1^{\frac{m}{x}} u^{\frac{\lambda_1}{\alpha} - 1} u^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u = CD \log \frac{m}{x}$$

and for  $x \leq \frac{m}{2}$ ,

$$\begin{aligned} A_1 &= CD \int_1^{\frac{m}{x}} u^{\frac{\lambda_1}{\alpha} - 1} (u - 1)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u \\ &\leq CD \int_1^2 (u - 1)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u + CD \int_2^{\frac{m}{x}} u^{\frac{\lambda_1}{\alpha} - 1} \left(\frac{u}{2}\right)^{\frac{\lambda_2}{\alpha} - 1} \mathrm{d}u \\ &= CD \frac{\alpha}{\lambda_2} + CD2^{1 - \frac{\lambda_2}{\alpha}} \log \frac{m}{2x} \end{aligned}$$

A similar analysis applies for x < 0. Therefore,

$$f(x) = \Theta(-\log|x|), \text{ as } x \to 0$$



Fig. 1. Steady-state densities of X in (16);  $\sigma_1 = \sigma_2 = 1$ ,  $\lambda_1 = \lambda_2$ .



Fig. 2. Log-log plot of steady-state densities of X in (16);  $\sigma_1 = \sigma_2 = 1$ ,  $\lambda_1 = \lambda_2$ . The reference straight lines with slop  $\frac{\lambda_1 + \lambda_2}{\alpha} - 1$  are superimposed on the plots.

## V. CONCLUSIONS

We presented some simple stochastic differential equations that lead to lower tail and/or upper tail power law behaviors. Some of the results are known but the derivations are different. We also presented a model with two opposite Poisson counters and an exponential decaying term. This model exhibits power law behavior near a critical point, which might be of interest to statistical physics.

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